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Personal Data

Birth: 1974
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Largo L. Lazzarino 1, 56100, Pisa, Italy

Education and Current Position

Associate Professor in Automatic Control and Robotics, Pisa University, since 2015

Ricercatore (Assistant Professor), Pisa University, 2007–2015

Ph.D. in Robotics and Industrial Automation, Pisa University, 2002

“Laurea” Degree in Mathematics, Pisa University, 1998

Researcher Contract (Assegno di Ricerca), at the Department of Electrical Systems and Automation Engineering Faculty of Pisa University in “Optimization techniques applied to the manipulation and the control of hybrid dynamical systems”, *2002-2006*

Visiting Researcher at Mechanical and Aerospace Engineering Department, University of California at Los Angeles, USA, Prof. E. Frazzoli, *11-12/2004.*

Visiting Scholar at the Laboratory for Information and Decision Systems, Massachusetts Institute of Technology, Cambridge USA, Prof. E. Feron, *10/2000-02/2001.*

Institutional Roles

Deputy Director of the Centro di Ricerca “E. Piaggio”, Università di Pisa, since January 2017.

Director of the “Advanced Manufacturing” CrossLab, Dipartimento di Eccellenza, Dipartimento di Ingegneria dell’Informazione da Marzo 2018.

Member of the Ph.D. school committee in “Ingegneria dell’Informazione”, Università di Pisa.

Academic Experiences

Professor of Distributed Robotic Systems for Robotics and Automation Engineering, Pisa University, *2011–2019*

Professor of Systems Theory and Control for Robotics and Automation Engineering, Pisa

University, *2016–2019*

Professor of Modelling and Simulation of Discrete Productive Systems Management Engineering and Robotics and Automation Engineering, Pisa University, *2018–2019*

Professor of Automatic Control Management Engineering, Pisa University, *2016–2019*

Professor of Systems Theory for Mechanical and Energy Engineering, Pisa University, *2015–2016*

Professor of Processes Control for Automation Engineering, Pisa University, *2009–2010*

Professor of System Theory for Management Engineering, Pisa University, *2008–2010*

Professor of Automatic Control for Management Engineering, Pisa University, *2006–2007*

Professor of Discrete Event Systems for Business Engineering and Computer Science Engineering, Siena University, *2006–2007*

Recent Research Projects

ILIAD: Intra-Logistics with Integrated Automatic Deployment: safe and scalable fleets in shared spaces (ILIAD, H2020-ICT 732737, Start: January 2017, Duration: 48 months). **Principal Investigator** for the University of Pisa.

WALKMAN: Whole-body Adaptive Locomotion and Manipulation (WALKMAN, FP7-ICT 611832, <http://www.walk-man.eu>, Start: September 2013, Duration: 48, Role: **WP Leader** months).

Control of Heterogeneous Automation Systems: Technologies for scalability, reconfigurability and security (CHAT, n. 224428, <http://www.ict-chat.eu/>, Start: September 1st, 2008, Duration: 36 months).

Cooperating Objects NETWORK of excellence (CONET NOE INFSO-ICT-224053, <http://www.cooperating-objects.eu/> Start: June 1st, 2008, Duration: 48 months)

HYCON2- Highly-Complex and Networked Control Systems (HYCON2 NOE ICT-257462, <http://www.hycon2.eu/> Start: September 1st, 2010, Duration: 48 months).

PLATform for the deployment and operation of heterogeneous NETWORKED cooperating objects (PLANET ICT-2009-2130, <http://www.planet-ict.eu/> Start: October 1st, 2010, Duration: 48 months).

Awards

Finalist of the “**ICRA Best Paper Award on Human-Robot Interaction**” for the paper “Deconfliction of Motion Paths with TrafficIns Inspired Rules in Robot-Robot and Human-Robot Interaction” by F. Celi, L. Wang, L. Pallottino, M. Egerstedt, published in IEEE Robotics and Automation Letters, vol. 4, no. 2, pp. 2227–2234, 2019.

Recipient of the “**2019 RAS Chapter of the Year Award**” as the Chair of the IEEE Robotics Automation Society Italian Chapter, with co-chair Andrea Maria Zanchettin.

Winner of the “**IEEE RAS Italian Chapter Young Author Best Paper Award 2009**” for the paper: Lucia Pallottino, Vincenzo G. Scordio, Antonio Bicchi, and Emilio Frazzoli, “Decentralized cooperative policy for conflict resolution in multivehicle systems,” on IEEE Transactions on Robotics, 23(6):1170–1183, 2007.

Top 10 Best Research Papers (2000 to 2009) in IEEE Transactions on Intelligent Transportation Systems: L. Pallottino, E. M. Feron, and A. Bicchi, “Conflict resolution problems for air traffic management systems solved with mixed integer programming,” IEEE Transactions on Intelligent Transportation Systems, vol. 3, no. 1, pp. 311, March 2002.

Recent Plenary and invited talks

Invited talk at Università di Modena e Reggio Emilia “Distributed approaches for multi mobile robot coordination”, 2018 14 November, Reggio Emilia.

Invited talk at IROS Workshop on “Robotics for logistics in warehouses and environments shared with humans”, presentation on “Soft robotic solutions for warehouse applications: from bin picking to palletizing”, 2018 October 4, Madrid, Spain.

Invited talk at the Workshop “Hybrid Dynamical Systems: Optimization, Stability and Applications”, 2017 January 9-11, Trento, Italy.

Keynote Speaker per “IEEE, 8th International Congress on Ultra Modern Telecommunications and Control Systems”, 19 October, 2016, Lisboa, Portugal.

Invited talk at the Università di Padova (March 31st 2016) “The Walk-Man humanoid robot: whole-body loco-manipulation planning and control”.

Roles and membership of Societies

IEEE Senior Member

Member of IEEE Robotics and Automation Society

Member of IEEE Control Systems Society

Member of IEEE Industrial Electronics Society

Chair of the Italian chapter of the IEEE Robotics and Automation Society (I-RAS) 2015–2018

Vice-chair of the Italian chapter of the IEEE Robotics and Automation Society (I-RAS) 2012–2014

Conferences and Workshops Organizing Committees

Co-Organizer

Registration and finance co-chair of the “29th Mediterranean Conference on Control and Automation”, Italy, June 22-25, 2021.

Workshops co-chair for the “Robotics: Science and Systems 2019”, Freiburg June 22-26, 2019.

Congress co-chair of Control Systems, Automation and Robotics track, 9th IEEE ICUMT 2017, Munich, Germany.

Program Chair of Workshop “2014 Modelling and simulation for autonomous systems” (MESAS14), Roma, 5-6 Maggio 2014.

Congress co-chair of Control Systems, Automation and Robotics track: 6th IEEE ICUMT 2014, St. Petersburg, Russia.

Co-Chair de CONET2012 Third International Workshop on Networks of Cooperating Objects April 16th, 2012 Beijing, China.

Co-Organizer of “Convegno Annuale dei Docenti e Ricercatori Italiani in Automatica: Automatica.it”, Pisa, 7-9 settembre 2011.

International Conferences Programme Committees:

IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS 2007, 2014, 2018, 2019);

IEEE Conference on Robotics and Automation (IEEE-ICRA 2011, 2014, 2015, 2017-2019);

Robotics: Science and Systems Conference (RSS 2014, 2015, 2018-Workshops);

IEEE Conference on Automation Science and Engineering (IEEE-CASE 2008-2010, 2017-2019);

IEEE International Symposium on Multi-robot and Multi-Agent Systems (MRS 2017);

2010 IEEE Intelligent Vehicles Symposium (IEEE-IVS 2010);

19th IEEE International Conference on Autonomous Robot Systems and Competitions (ICARSC 2019);

2015 Modelling and simulation for autonomous systems workshop (MESAS15);

Intelligent Robotics and Multi-Agent Systems (IRMAS 2015, 2016)

International Conference on INnovations in Intelligent SysTems and Applications (INISTA 2014);

International Workshop on Networks of Cooperating Objects CONET (2010, 2011 and 2013);

Autonomous Agents and MultiAgent Systems 2011-2013, ARMS@AAMAS2011, ARMS2012, ARMS2013;

1st International Workshop on Robotics IEEE International Conference on Service Operations and Logistics, and Informatics (IEEE SOLI, 2017) Technology Transfer: Innovation from Academia to Industry (RTT 2015)

1st International Conference on Intelligent Robotics Automation and Manufacturing 2012 (IRAM2012)

CMASA - Cooperative Multi-Agent Systems and Applications track of the ACM Symposium on Applied Computing (SAC 2013, 2015, 2017-2019)

Robotica – International Conference on Autonomous Robot Systems 2013 and 2014

IEEE Conference on Control Applications (CCA 2014, 2015)

The 8th International Symposium on Distributed Autonomous Robotic Systems 2006 (DARS06);

Reviewer Activities

International Journals' Editorial Board:

- IEEE Robotics and Automation Letters, (2018- on going);
- IEEE Transactions on Robotics(2013-2017)
- International Journal of Advanced Robotic Systems (2013-2015)

International Journals' reviewer:

- Automatica,
- IEEE Transactions on Automatic Control,
- IEEE Transactions on Robotics,
- IEEE Robotics and Automation Magazine,
- IEEE Robotics and Automation Letters;
- International Journal of Robotics Research;

- IEEE Transactions on Automation Science and Engineering
- SIAM Journal On Control and Optimization (SICON),
- Autonomous Robots (Springer),
- Robotics and Autonomous Systems (Elsevier);
- Control Engineering Practice (Elsevier);
- Operations Research & Decision Theory;
- IEEE Transaction on Intelligent Transportation Systems,
- IEEE Transactions on Systems, Man and Cybernetics,
- IEEE Transactions on Control of Network Systems
- IFAC Journal on Control Engineering Practice,
- IEEE Transactions on Control System Technology,
- IEEE Transactions on Industrial Informatics;
- Journal of Intelligent and Robotic Systems;
- AIAA Journal of Guidance, Control, and Dynamics;
- Annals of Operations Research;
- European Journal of Operational Research;
- Information Sciences, Elsevier.

Reviewer of Handbook of Robotics.

Reviewer of Ph.D. Thesis of the European Embedded Control Institute Award, 2009.

Reviewer of Ph.D. thesis for Università di Trento, KTH Stockholm, Università di Padova, Politecnico di Milano, Sapienza Università di Roma.

Research Projects Reviewer:

- External Reviewer for the Portuguese Foundation for Science and Technology (FCT) for research projects in the Computer Sciences and Engineering field, 2010.
- Reviewer for the Natural Sciences and Engineering Research Council of Canada (NSERC) for “Discovery Grant” research projects, 2012.
- Reviewer for the Fund for Scientific Research (F.R.S.-FNRS), 2013, 2015, 2017.
- Evaluator of EU projects proposals, 2018.

Main Research Interests

- Planning and Control of Humanoid Robots
- Distributed coordination and control of multi vehicle systems
- Distributed collision avoidance in multi-agent systems
- Optimal control of constrained robotic systems
- Controllability and motion planning of robots formations

Publications

Journals or Books' Chapters

1. C. Della Santina, L. Pallottino, D. Rus, A. Bicchi, "Exact task execution in highly under-actuated soft limbs: an operational space based approach", *IEEE Robotics and Automation Letters*, Vol. 4 n. 3, pp. 2508-2515, 2019.
2. F. Celi, L. Wang, L. Pallottino, M. Egerstedt, "Deconfliction of Motion Paths with Traffic Inspired Rules in Robot-Robot and Human-Robot Interactions", *IEEE Robotics and Automation Letters*, Vol. 4 n. 2, pp. 2227-2234, 2019.
3. M. Razzanelli, E. Crisostomi, L. Pallottino, G. Pannocchia, "Distributed model predictive control for energy management in a network of microgrids using the dual decomposition method", *Optimal Control Applications and Methods*, pp. 1-17, 2019.
4. S. Nardi, F. Mazzitelli, L. Pallottino, "A Game Theoretic Robotic Team Coordination Protocol For Intruder Herding", *IEEE Robotics and Automation Letters*, Vol. 3, n. 4, pp. 4124-4131, 2018.
5. M. Tognon, C. Gabellieri, L. Pallottino, A. Franchi, "Aerial Co-Manipulation With Cables: The Role of Internal Force for Equilibria, Stability, and Passivity", *IEEE Robotics and Automation Letters*, Vol. 3, n. 3, pp. 2577 - 2583, 2018.
6. F. Negrello, A. Settimi, D. Caporale, G. Lentini, M. Poggiani, D. Kanoulas, L. Muratore, E. Luberto, G. Santaera, L. Ciarleglio, L. Ermini, L. Pallottino, D. G Caldwell, N. Tsagarakis, A. Bicchi, M. G. Catalano, "WALK-MAN Humanoid Robot: Field Experiments in a Post-earthquake Scenario", *IEEE Robotics & Automation Magazine*, vol 25,n 3, pp 8-22, 2018.
7. N. G. Tsagarakis, F. Negrello, M. Garabini, W. Choi, L. Baccelliere, V. G. Loc, J. Noorden, M. Catalano, M. Ferrati, L. Muratore, P. Kryczka, E. Mingo Hoffman, A. Settimi, A. Rocchi, A. Margan, S. Cordasco, D. Kanoulas, A. Cardellino, L. Natale, H. Dallali, J. Malzahn, N. Kashiri, V. Varricchio, L. Pallottino, C. Pavan, J. Lee, A. Ajoudani, D. G. Caldwell, A. Bicchi, "WALK-MAN Humanoid Platform", *The DARPA Robotics Challenge Finals: Humanoid Robots To The Rescue*. Editors Spenko M., Buerger S., Iagnemma K., Springer Tracts in Advanced Robotics, vol 121, pp 495-548, Springer.
8. A. Cristofaro, P. Salaris, L. Pallottino, F. Giannoni and A. Bicchi, "On the Minimum-Time Control Problem for Differential Drive Robots with Bearing Constraints", *Journal of Optimization Theory and Applications*, pp. 1-27, 2017.
9. N. G. Tsagarakis, D. G. Caldwell, F. Negrello, W. Choi, L. Baccelliere, V. G. Loc, J. Noorden, L. Muratore, A. Margan, A. Cardellino, L. Natale, E. Hoffman Mingo, H. Dallali, N. Kashiri, J. Malzahn, J. Lee, P. Kryczka, D. Kanoulas, M. Garabini, M. G. Catalano, M. Ferrati, V. Varricchio, L. Pallottino, C. Pavan, A. Bicchi, A. Settimi, A. Rocchi, and A. Ajoudani, "WALK-MAN: A High-Performance Humanoid Platform for Realistic Environments", *Journal of Field Robotics*, vol. 34, no. 4, pp. 1 - 34, 2017.
10. H. Marino, P. Salaris, and L. Pallottino, "Controllability analysis of a pair of 3D Dubins vehicles in formation", *Robotics and Autonomous Systems*, vol. 83, pp. 94-105, 2016.
11. M. Ferrati, A. Settimi, L. Muratore, A. Cardellino, A. Rocchi, E. Mingo Hoffman, C. Pavan, D. Kanoulas, N.G. Tsagarakis, L. Natale, and L. Pallottino, "The Walk-Man Robot Software Architecture", *Frontiers in Robotics AI*, 2016.
12. P. Salaris, A. Cristofaro, and L. Pallottino, "Epsilon-Optimal Synthesis for Unicycle-like Vehicles with Limited Field-Of-View Sensors", *IEEE Transactions on Robotics (T-RO)*, vol. 31, no. 6, pp. 1404 - 1418, 2015.

13. P. Salaris, A. Cristofaro, L. Pallottino, and A. Bicchi, “Epsilonoptimal synthesis for vehicles with vertically bounded Field-Of-View”, *IEEE Transactions on Automatic Control*, vol. 60, no. 5, pp. 1204 - 1218, 2015.
14. S. Martini, D. Di Baccio, F. Alarcón-Romero, A. Viguria-Jiménez, L. Pallottino, G. Dini, and A. Ollero, “Distributed motion misbehavior detection in teams of heterogeneous aerial robots”, *Robotics and Autonomous Systems information*, vol. 74 part A, pp. 30-39, 2015.
15. P. Salaris, L. Pallottino, and A. Bicchi, “Shortest Paths for Finned, Winged, Legged and Wheeled Vehicles with Side-Looking Sensors”, *International Journal of Robotics Research*, 31(8):997-1017, 2012.
16. A. Bicchi, A. Fagiolini, and L. Pallottino, “Towards a Society of Robots: Behaviors, Misbehaviors, and Security”, *IEEE Robotics and Automation Magazine*, 17(4):26 - 36, December 2010.
17. P. Salaris, D. Fontanelli, L. Pallottino and A. Bicchi, “Shortest Paths for a Robot with Non-holonomic and Field-of-View Constraints”, *IEEE Trans. on Robotics*, 26(2):269 - 281, 2010.
18. A. Bicchi, A. Danesi, G. Dini, S. La Porta, L. Pallottino, I. M. Savino, and R. Schiavi, “Heterogeneous Wireless Multirobot System”, *Robotics and Automation Magazine, IEEE*, 15(1):62-70, 2008.
19. L. Pallottino, V. G. Scordio, E. Frazzoli, and A. Bicchi, “Decentralized cooperative policy for conflict resolution in multi-vehicle systems”. *IEEE Trans. on Robotics*, 23(6):1170-1183, 2007.
20. A. Bicchi, A. Caiti, L. Pallottino, G. Tonietti, “Online Robotic Experiments for Tele-Education at the University of Pisa”, *Int. Journal of Robotic Systems*, 22(4):217-230, 2005. Note: Special issue on Internet & Online Robots for Telemanipulation.
21. L. Pallottino, E. Feron, A. Bicchi, “Conflict Resolution Problems for Air Traffic Management Systems Solved with Mixed Integer Programming”, *IEEE Transaction on Intelligent Transportation Systems*, vol. 3, no. 1, pp. 3-11, March 2002.
22. S. Pancanti, L. Leonardi, L. Pallottino, A. Bicchi, “Optimal control of quantized input systems”, M. Greenstreet and C. Tomlin, editors, *Hybrid Systems: Computation and Control*, LNCS 2289 Lecture Notes in Computer Science. Springer-Verlag, Heidelberg, Germany, pp. 351-363, 2002.
23. A. Bicchi and L. Pallottino, “On Optimal Cooperative Conflict Resolution for Air Traffic Management Systems”, *IEEE Transaction on Intelligent Transportation Systems*, vol. 1, no.4, pp.221-231, Dec. 2000.
24. A. Bicchi and L. Pallottino, “Optimal planning for coordinated vehicles with bounded curvature”, In B. Donald, K. Lynch, and D. Rus, editors, *Algorithmic and Computational Robotics: New Directions*, volume 1, pages 167-172, 2000.

Conference Proceedings

1. D. Caporale, Settini, A., Massa, F., Amerotti, F., Corti, A., Fagiolini, A., Guiggiani, M., Bicchi, A., and L. Pallottino, “Towards the Design of Robotic Drivers for Full-Scale Self-Driving Racing Cars”, 2019 International Conference on Robotics and Automation (ICRA). 2019.
2. C. Gabellieri, M. Tognon, L. Pallottino and A. Franchi, “A Study on Force-Based Collaboration in Flying Swarms”, in *Proc. Swarm Intelligence* ed. Dorigo, Birattari et al., Springer International Publishing, pp 3-15, 2018.

3. D. Caporale, A. Fagiolini, L. Pallottino, A. Settimi, A. Biondo, F. Amerotti, F. Massa, S. De Caro, A. Corti and L. Venturini, "A Planning and Control System for Self-Driving Racing Vehicles", in Proc. of 2018 IEEE 4th International Forum on Research and Technology for Society and Industry (RTSI), pp 1-6, 2018.
4. L. Silvestri, L. Pallottino, S. Nardi, "Design of an indoor autonomous robot navigation system for unknown environments", in International Workshop on Modelling and Simulation for Autonomous Systems MESAS 2017, Rome, Italy, 24-26 October 2017, Lecture Notes in Computer Science 10756 (LNCS), pp. 153-169, 2018.
5. A. Mannucci, S. Nardi, L. Pallottino, "Autonomous 3D exploration of large areas: A cooperative frontier-based approach", in International Workshop on Modelling and Simulation for Autonomous Systems MESAS 2017, Rome, Italy, 24-26 October 2017, Lecture Notes in Computer Science 10756 (LNCS), pp. 18-39, 2018.
6. M. Bonilla, L. Pallottino and A. Bicchi, "Noninteracting Constrained Motion Planning and Control for Robot Manipulators", in IEEE International Conference on Robotics and Automation (ICRA 2017), Singapore, 29 May - 3 June, pp. 4038-4043, 2017.
7. T. Fabbri, E. Simetti, G. Casalino, L. Pallottino, and A. Caiti, "Distributed Task-priority Based Control in Area Coverage & Adaptive Sampling", in MTS/IEEE Oceans 2017, Aberdeen, Scotland, June 2017, 2017.
8. A. Settimi, D. Caporale, P. Kryczka, M. Ferrati, L. Pallottino, "Motion Primitive Based Random Planning for LocoManipulation Tasks", in IEEE International Conference on Humanoid Robots (HUMANOIDS 2016), Cancun, Mexico, 15-17 Nov. 2016 , 2016.
9. G. M. Gasparri, F. Fabiani, M. Garabini, L. Pallottino, M.G. Catalano, G. Grioli, R. Persichini, and A. Bicchi, "Robust Optimization of System Compliance for Physical Interaction in Uncertain Scenarios", in IEEE International Conference on Humanoid Robots (HUMANOIDS2016), Cancun, Mexico, 15-17 Nov. 2016 , 2016.
10. M. Ferrati, H. Marino, A. Settimi, S. Nardi, and L. Pallottino, "Multiobject handling for robotic manufacturing", in IECON 2016: 42nd Annual Conference of the IEEE Industrial Electronics Society, Florence, Italy, October 24-27.
11. S. Nardi, T. Fabbri, A. Caiti, and L. Pallottino, "A game theoretic approach for antagonistic-task coordination of underwater autonomous robots in asymmetric threats scenarios", in OCEANS 2016, 2016.
12. A. Ferrarelli, D. Caporale, A. Settimi, and L. Pallottino. "APRICOT: Aerospace PRototypIng COntrol Toolbox. A Modeling and Simulation Environment for Aircraft Control Design", in International Workshop on Modelling and Simulation for Autonomous Systems MESAS 2016, Rome, Italy, June 15-16, 2016, 2016, vol. 9991 of the book series Lecture Notes in Computer Science (LNCS), pp. 139 - 157.
13. T. Fabbri, S. Nardi, L. Isgrò, L. Pallottino, and A. Caiti, "Assessing the Potential of Autonomous Multi-agent Surveillance in Asset Protection from Underwater Threats", in International Workshop on Modelling and Simulation for Autonomous Systems MESAS 2016, Rome, Italy, June 15-16, 2016, 2016, vol. 9991 of the book series Lecture Notes in Computer Science (LNCS), pp. 204 - 213.
14. A. Faralli, N. Giovannini, S. Nardi, and L. Pallottino, "Indoor Real-Time Localisation for Multiple Autonomous Vehicles Fusing Vision, Odometry and IMU Data", in International Workshop on Modelling and Simulation for Autonomous Systems MESAS 2016, Rome, Italy, June 15-16, 2016, 2016, vol. 9991 of the book series Lecture Notes in Computer Science (LNCS), pp. 288 - 297.

15. S. Nardi, and L. Pallottino, “NoStop: An Open Source Framework for Design and Test of Coordination Protocol for Asymmetric Threats Protection in Marine Environment”, in International Workshop on Modelling and Simulation for Autonomous Systems MESAS 2016, Rome, Italy, June 15-16, 2016, 2016, vol. 9991 of the book series Lecture Notes in Computer Science (LNCS), pp. 176 - 185.
16. S. Nardi, C. Della Santina, D. Meucci, and L. Pallottino, “Coordination of unmanned marine vehicles for asymmetric threats protection”, in MTS/IEEE Oceans 2015, May 18-21, Genoa, Italy, 2015.
17. M. Bonilla, E. Farnioli, L. Pallottino, and A. Bicchi, “Sample-Based Motion Planning for Robot Manipulators with Closed Kinematic Chains”, in IEEE International Conference on Robotics and Automation (ICRA2015), Seattle, USA, 25 - 30 May, 2015, pp. 2522 - 2527.
18. G. M. Gasparri, M. Garabini, L. Pallottino, L. Malagia, M. G. Catalano, G. Grioli, and A. Bicchi, “Variable Stiffness Control for Oscillation Damping”, in IEEE International Conference of Intelligent Robots and Systems (IROS2015), Hamburg, Germany, September 28 - October 02, 2015, 2015, pp. 6543 - 6550.
19. M. Ferrati, A. Settini, and L. Pallottino, “ASCARI: a component based simulator for distributed mobile robot systems”, in Modelling & Simulation for Autonomous Systems - MESAS2014, Rome, 5-6 May 2014, 2014, vol. Lecture Notes in Computer Science, Volume 8906, 2014, pp. 152-163.
20. A. Cristofaro, P. Salaris, L. Pallottino, F. Giannoni, and A. Bicchi, “On Time-Optimal Trajectories for Differential Drive Vehicles with Field-Of-View Constraints”, in IEEE Conference on Decision and Control (CDC2014), Los Angeles, USA, December 15-17, 2014, pp. 2191 - 2197.
21. T. Rizano, D. Fontanelli, L. Palopoli, L. Pallottino, and P. Salaris, “Global Path Planning for Competitive Robotic Cars”, In IEEE Conference on Decision and Control 2013, Florence, Italy, p. 4510 - 4516.
22. P. Salaris, A. Cristofaro, L. Pallottino, and A. Bicchi, “Shortest paths for wheeled robots with limited Field-Of-View: introducing the vertical constraint”, In IEEE Conference on Decision and Control 2013, Florence, Italy, p. 5143 - 5149.
23. A. Settini and L. Pallottino, “A Subgradient Based Algorithm for Distributed Task Assignment for Heterogeneous Mobile Robots”, In IEEE Conference on Decision and Control 2013, Florence, Italy, p. 3665 - 3670.
24. M. Ferrati and L. Pallottino, “A time expanded network based algorithm for safe and efficient distributed multi-agent coordination”, In IEEE Conference on Decision and Control 2013, Florence, Italy, p. 2805 - 2810.
25. L. Cancemi, A. Fagiolini, and L. Pallottino, “Distributed Multilevel Motion Planning for Autonomous Vehicles in Large Scale Industrial Environments”, In IEEE International Conference on Emerging Technologies & Factory Automation (ETFA), 2013, p. 1-8.
26. H. Marino, M. Bonizzato, R. Bartalucci, P. Salaris, and L. Pallottino, “Motion Planning for Two 3D-Dubins Vehicles with Distance Constraint”, In International Conference of Intelligent Robots and Systems - IROS 2012, Vilamoura, Algarve, Portugal, 2012, p. 4702 - 4707.
27. P. Salaris, L. Pallottino, S. Hutchinson, A. Bicchi, “From Optimal Planning to Visual Servoing With Limited FOV”, IEEE/RSJ International Conference on Intelligent Robots and Systems, pages 2817 - 2824, 2011.

28. S. Manca, A. Fagiolini, and L. Pallottino, “Decentralized Coordination System for Multiple AGVs in a Structured Environment”, In 2011 Congress of the International Federation of Automatic Control, Milano, Italy, pages 6005 - 6010, August 28 - September 2 2011.
29. P. Salaris, L. Pallottino, and A. Bicchi, “Shortest Paths With Side Sensor”, In 2011 IEEE International Conference on Robotics and Automation, Shanghai, China, pages 4875 - 4882, May 9 - 13 2011.
30. H. Wang, L. Pallottino, and A. Bicchi, “Controllability Properties for Aircraft Formations”, In Proc. IEEE Conference on Decision and Control 2010, pages 2047 - 2054, 2010.
31. H. Wang, L. Pallottino, and A. Bicchi, “Motion planning for Formations of Dubins Vehicles”, In Proc. IEEE Conference on Decision and Control 2010, pages 2263 - 2269, 2010.
32. H. Wang, L. Pallottino, and A. Bicchi, “Controllability for Pairs of Vehicles Maintaining Constant Distance”, In IEEE International Conference on Robotics and Automation (ICRA2010), Anchorage, Alaska, pages 342 - 349, May 3 - 8 2010.
33. L. Pallottino, P. Salaris, D. Fontanelli, and A. Bicchi, “Shortest Paths for Non-holonomic Vehicles with Limited Field of View Camera”, In Proc. IEEE Conference on Decision and Control, Shanghai, China, pages 8434 - 8439, December, 16 - 18 2009.
34. P. Alriksson, J. Nordh, K.-E. Arzén, A. Bicchi, A. Danesi, R. Schiavi and L. Pallottino, “A Component-Based Approach to Localization and Collision Avoidance for Mobile Multi-Agent Systems”, Proc. European Control Conference (ECC), pages 4285-4292, July 2007.
35. A. Balestrino and L. Pallottino, “Higher order method for non linear equations resolution: application to mobile robot control”, In Proc. European Control Conference, pp. 3628-3634, 2007.
36. A. Fagiolini, G. Valenti, L. Pallottino, G. Dini, and A. Bicchi, “Decentralized Intrusion Detection for Secure Cooperative Multi-Agent Systems”, In Proc. IEEE Int. Conf. on Decision and Control, pages 1553-1558, 2007.
37. A. Fagiolini, G. Valenti, L. Pallottino, G. Dini, and A. Bicchi, “Local Monitor Implementation for Decentralized Intrusion Detection in Secure Multi-Agent Systems”, In 3rd IEEE Conference on Automation Science and Engineering, pages 454-459, 2007.
38. L. Pallottino and A. Bicchi, “A Dynamic Programming Approach to Optimal Planning for Vehicles with Trailers”, In Proc. IEEE Int. Conf. on Robotics and Automation, pages 3098-3103, 2007.
39. L. Pallottino, A. Bicchi, and E. Frazzoli, “Probabilistic verification of decentralized multi-agent control strategies: a case study in conflict avoidance”, In American Control Conference (ACC), pages 170-175, 2007.
40. A. Danesi, A. Fagiolini, I. Savino, L. Pallottino, R. Schiavi, G. Dini, and A. Bicchi, “A scalable platform for safe and secure decentralized traffic management of multiagent mobile systems”, In ACM Workshop on Real-World Wireless Sensor Networks, 2006.
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